1. Use the autopilot to fly to +41.82 latitude, -98.95 longitude, 10000 feet altitude

2. Display the name of the city that is currently beneath the Pod.

3. Launch a dropsonde

4. Close the dropsonde viewer

5. Press the ‘r’ key to reset your position to the starting point

6. Display the grid points

7. Set the grid point density so that every 50\textsuperscript{th} point is displayed

8. Pick any grid point and fly to it as efficiently as possible

9. Launch a second dropsonde

10. Pick any grid point and fly to it as efficiently as possible (if none in view, turn the pod until you see some)

11. Launch a third dropsonde

12. Turn the Pod to point due East

13. Move the Pod forward a short distance

14. Launch a fourth dropsonde

15. View the first dropsonde’s display

16. Delete the second dropsonde

17. Close the dropsonde display

18. Turn off grid points

19. Click the “Done” button